The Motion Coordinator system is extremely modular, allowing the user to tailor the controller to their specific applications, this also allows the flexibility to incorporate new modules if the need should change, making the system "future proof". Systems may be used with a stand alone program or alternatively commands can be sent from an external computer.

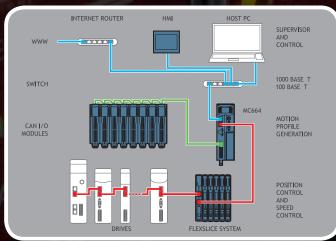
All Motion Coordinators, whether panel mount, rack mount, DIN-rail mount or a custom design format, allow digital or analogue I/O expansion with Trio's I/O modules. Special I/O requirements can also be accommodated using the CANopen protocol to control third party I/O modules. The Flexslice System offers fast high performance EtherCAT devices for Trio's range of EtherCAT Motion Coordinators.

Trio's UNIPLAY range of operator interfaces provide a robust and functional HMI using the Ethernet network. Third party HMI products, touchscreens, etc. can communicate to the *Motion Coordinator* via the Modbus-RTU serial protocol.

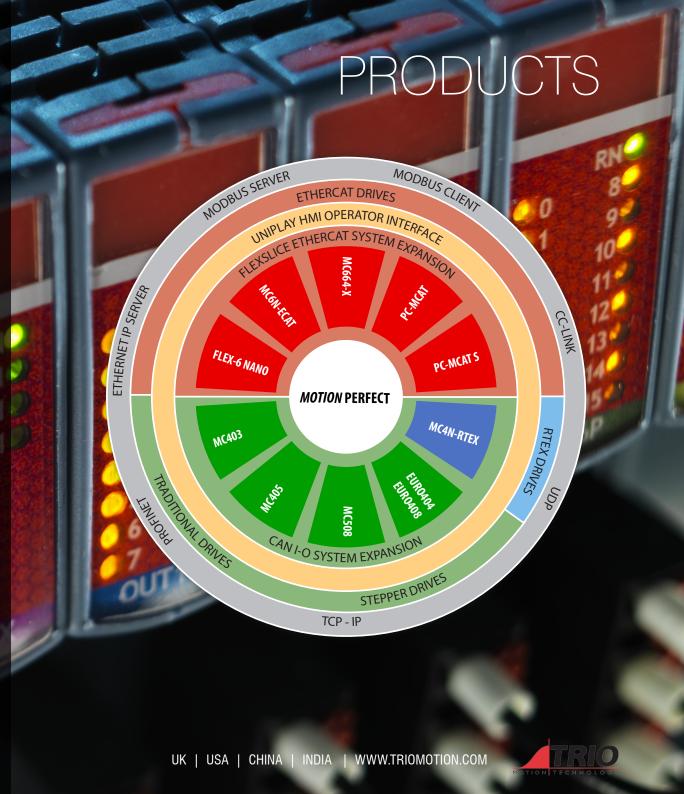
System Set-Up

The MC4/5/6 range includes advanced networking technology for connection to Digital Servos, CANbus and Factory Networks. Access to all parts of the system by network connections allows reduced down-time with automated fault reporting and analysis.

With a MC664 Motion Coordinator, it is possible to control a machine with up to 128 axes (64 stepper/servo and 64 virtual), 1024 digital inputs, 1024 digital outputs, 32 analogue inputs and 16 analogue outputs.

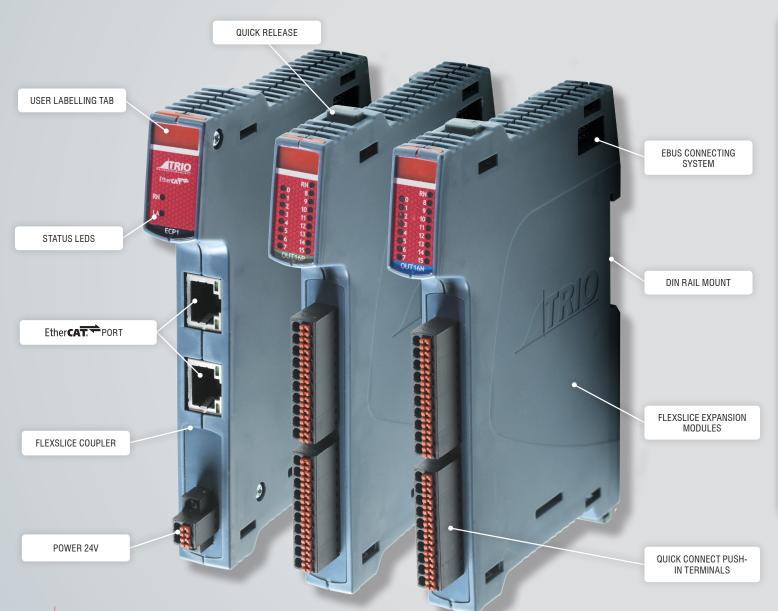


Preliminary specifications may change without notice



Flexslice System Flexible EtherCAT Devices





FEATURES

- **★** Use with Trio or 3rd Party EtherCAT Masters
- ★ High Performance, Flexible Topology and Simple Configuration
- **★** Bus Cycle Time Synchronised with Motion Coordinator Servo Period
- ★ Bus Coupler Module with 2x RJ45 Ethernet Ports For Ethercat Connection
- ★ Ethercat Protocol Remains Fully Intact Down to Individual Modules Using the E-Bus System
- ★ I/O Functions Tightly Synchronised to Motion Using Ethercat Distributed Clocks
- ★ Automatic Mapping to the *Motion Coordinator* I/O System
- * DIN Rail Mounted
- ★ Multiple Practical Push-In Connector Options – No Break Outs Required
- ★ Clip-Together Design With 'Quick Release' Locks For Mechanical Integrity
- **★** User Labelling Facility
- ★ Machine Builder Custom Functionality Options



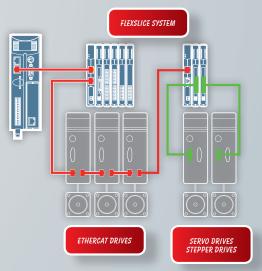
The EtherCAT Flexslice System is designed to let you do more! It offers fast flexible expansion for motion applications and can be used with Trio or 3rd Party Masters.

Trio's Flexslice input/output modules provide a robust, high speed and flexible solution for both motion control and general automation. EtherCAT cycle times down to 250μ secs are supported and the bus coupler uses EBUS technology to bring all the sub-modules on to the EtherCAT network with no degradation in performance.

The Flexslice system makes available a selection of digital and analogue I/O terminals as well as motion modules with pulse + direction outputs designed for precise positioning of stepper and servo motors via suitable drive technology.

The digital I/O modules have high-speed functionality. In addition, analogue modules and axis modules may be fitted to make a superbly tailored system that can be placed remotely from the master if needed.

All Flexslice modules support automatic addressing with the master to automatically detect and configure the modules on startup. The bus coupler can support up to 16 input/output modules which have a positive mechanical lock and bus connector, making a reliable EBUS connection through the backplane. The complete assembly can be DIN rail mounted.



The Flexslice system begins with the coupler. The coupler is connected to the

network via the upper Ethernet interface. The lower RJ45 socket may be used to connect further EtherCAT devices in the same strand.

In the EtherCAT network. the P366 coupler can be installed in any position in the Ethernet string; making it suitable for operation close to the master or at a remote position.



identification, each Flexslice module incorporates removable tab that can be written on. It simply slides in and out of a slot at the top of each

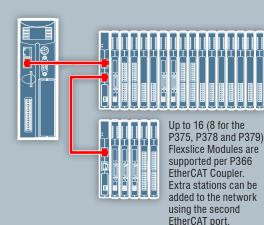
metal chassis provides a good earth from the pcb of each module to the DIN rail to reduce noise and dissipate heat.



programmable FPGA allows customisation of the functionality of some Flexslice Modules using Motion Perfect v4. The program can be "locked-down" creating a unique function for a machine builder which protects the functionality from being copied.



The positive "click-to-lock" mechanism firmly clamps Flexslice modules to each other to form a Flexslice station. Simply push each module together and slide the quick release locks into position.





Flexslice System Flexible EtherCAT Devices

P366: ETHERCAT COUPLER

The P366 Flexslice EtherCAT Coupler connects EtherCAT with the EtherCAT slices. One station consists of a P366 Coupler and up to 16 Flexslice EtherCAT modules. The Coupler converts the passing telegrams from Ethernet 100BASE-T to EBUS signal format.

Power supply 24V DC, 0.8A min for requirement full system

EtherCAT RJ45 Connection

Protocol EtherCAT

Data rate 100 Mbit/s

Dimensions 17.2w x 147h x 107d

(mm)

Weight 160g

Network Cable CAT5e min

Compliance RoHS, CE and UL



ECP1

PRODUCT CODES:

P366 Flexslice EtherCAT Coupler

P371 Flexslice 16-Out PNP

P372 Flexslice 16-In PNP

P375 Flexslice Flex 3-Axis

P376 Flexslice 16-Out NPN

P377 Flexslice 16-In NPN

P378 Flexslice 8 Analogue Outputs

P379 Flexslice 8 Analogue Inputs

P367 Flexslice Thermocouple *

P373 Flexslice 8-In 8-Out*

P374 Flexslice Analogue 2 Servo Axes*

* Coming soon

P371: 16-OUT PNP

The P371 digital output Flexslice connects the binary control signals from the Motion Coordinator to the machine's output devices at 24V DC. All 16 outputs are current sourcing (PNP) type and have electrical isolation. Outputs and power connection are via 2 x single-row push-in connectors. The Flexslice module indicates the output signal states via LEDs.

Module current 110mA max consumption

(EBUS 5V)

Number of 16 (2 banks of 8) **Digital Outputs**

requirement

Power supply 24V (+/-20%) DC

Load type Resistive.

inductive and capacitive

"ON" time 110us (10% to 90%)

"OFF" time 210us (90% to

10%)

Max. Output 0.5A per channel current

Max. Output 4A per bank of 8

current Outputs

Protection

Short—Circuit 1.4A typ per output

Over voltage Yes Protection

Reverse Yes Voltage Protection

P372: 16-IN PNP

The P372 digital input Flexslice connects 24V DC signals from devices on the machine to the binary control registers in the Motion Coordinator. All 16 inputs are current sinking (PNP) type and have electrical isolation. Inputs and power connection are via 2 x single-row push-in connectors. The Flexslice module indicates the input signal states via LEDs.

Module current 100mA max consumption

(EBUS 5V)

Number of 16 (2 banks of 8) Digital Inputs

Power supply 24V (+/-20%) DC requirement

"ON" Voltage 11.2V tvp threshold

"OFF" Voltage 10.2V typ

threshold

Input current 3.5mA typ

Input filter 18KHz

Cut-off (RC network)

P375: FLEX 3-AXIS

The P375 Flex 3 Axis Module allows up to 3 stepper motors or encoders to be connected to a control system. It supports incremental encoders. If configured for stepper / pulse output an axis can be pulse+direction or quadrature simulated encoder output. A single MDR connector provides a reliable shielded 26 way connector for high speed signals. The P375 is compatible with most high-resolution microstep drives.

Max Step Rate 8MHz pulse count

Step / Pulse Pulse Control or Width Square Wave

Max Enc Rate 8MHz encoder count

Module current 150mA max

consumption (EBUS 5V)

Field Yes Programmable

Step/Enc Port MDR Connector

0...5V

Max Axes 3 (software configurable)

WDOG Output Yes





P376: 16-OUT NPN

The P376 digital output Flexslice connects the binary control signals from the Motion Coordinator to the machine's output devices, such as relays, contactors, valves, lamps etc. at 24V dc. All 16 outputs are current sinking (NPN) type and have electrical isolation. Outputs and power connection are via 2 x single-row push-in connectors. The Flexslice module indicates the output signal states via LEDs.

Module current 110mA max consumption

(EBUS 5V)

Number of 16 (2 banks of 8) Digital Outputs

requirement

Power supply 24V (+/-20%) DC

Load type Resistive, inductive and capacitive

"ON" time 75us (90% to 10%)

"OFF" time 105us (10% to

(typ) 90%)

Max. Output 0.5A per channel current

Max. Output 4A per bank of 8 current Outputs

Short-Circuit 3A typ per output Protection

Over voltage Yes Protection

> Reverse Yes Voltage Protection

P377: 16-IN NPN

The P377 digital input Flexslice connects 24V dc signals from devices on the machine to the binary control registers in the *Motion* Coordinator. All 16 inputs are current sourcing (NPN) type and have electrical isolation. Inputs and power connection are via 2'x singlerow push-in connectorss. The Flexslice module indicates the input signal states via LEDs.

Module current 100mA max consumption

(EBUS 5V)

Number of 16 (2 banks of 8) Digital Inputs

Power supply 24V (+/-20%) DC requirement

"ON" Voltage 13.7V typ threshold

"OFF" Voltage 14.6V typ threshold

Input current 3.5mA

Input filter 18KHz Cut-off (RC network)

P378: 8 ANALOGUE OUTPUTS

The P378 Flexslice 8 Analogue Output module has eight programmable voltage range output terminals, each digitised to a resolution of 12 bit. The 8 single ended outputs have a common OV potential and are brought out to a single push-in connector.

Power Supply via the EBUS

Module current 200mA max consumption (EBUS 5V)

Signal voltage -10...+10V; 0...+10V

Signal current +/-6mA max

Resolution 12 bit

Output 0.5ohm impedance

Number of 8 Analogue Ouputs

P379: 8 ANALOGUE INPUTS

The P379 Flexslice 8 Analogue Input module has eight programmable voltage range input terminals, each digitised to a resolution of 12 bit. The 8 single ended inputs have a common OV potential and are brought out to a single row push-in connector.

Power Supply via the EBUS

Module current 160mA max consumption (EBUS 5V)

Signal voltage -10...+10V; 0...+10V

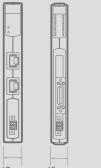
Signal current 0...20mA

Resolution 12 bit

Overvoltage ±25V protection

Number of 8 Inputs

OVERALL DIMENSIONS





ALL FLEXSLICE MODULES

Connectors Push-in

Cable length (max) 30m

Dimensions (mm) 15w x 147h x 107d

Weight 145 g

EtherCAT refresh ≥ 125us cycle

Isolation 1KV

Compliance RoHS and CE